Application Data Sheet

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Application Information

Title: LABEL SWITCHED PATH OAM WRAPPER

Shapiro Cohen Docket Number: 583P21US

LABEL SWITCHED PATH OAM WRAPPER

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Field of the Invention

[0001] The invention relates to communications networks and, more particularly, to methods and devices for determining the performance of network segments in an Multi-Protocol Label Switched (MPLS) network.

Background to the Invention

[0002] Today's increasing use of and reliance on communications networks has led to the development of new standards and protocol that provide more reliable and efficient network services to consumers.

A standard that is still developing is MPLS (Multi-Protocol Label Switching). This emerging standard allows packets or any data transmission units (DTUs) to be routed in the MPLS network based simply on a label that the DTU is carrying. This process facilitates the complexity of route lookups that are based on a destination IP (Internet Protocol) address. Thus, a DTU (Data Transmission Unil) arriving at a router is forwarded to another router based merely on the a DTU's label. At the next router, the label of the DTU may be replaced or added to for the next "hop" in the DTU's travel towards its ultimate destination. While the MPLS standard promises great henefits, very few methods have been developed for fault detection/management of an MPLS network.

[0004] One solution to the above need has been suggested by ITU-T Y.1711. In this document, discussed is the use of a special Operation And Maintenance (CAM) packet that can be used to

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determine the performance of an MPLS network. An unused reserved MPLS label value is used at the bottom of the label stack of OAM packets to delineate CAM packets for transport between Label Switch Path (LSP) ingress and egress points. This approach, unfortunately, only allows for performance determination between these ingress and egress points. The performance of network segments between these ingress and egress points is not possible nor even considered in the above proposal. Furthermore, the use of a specific MPLS label value for CAM packets leads to increased overhead costs for this proposal.

[00051 By way of explanation, it should be noted that an LSP is a specific data traffic path in an MPLS network. Such LSPs are provided for by LDPs (Label Distribution Protocols) that establish these paths and reserves the necessary resources on the nodes in the path to meet predefined service requirements of the data path. An LSP is analogous to the route that a packet or DTU is tasked to follow in being transmitted from an ingress (entry) LSP node to an egress (axit) LSP node. LSPs are established from the egress LSP node to the ingress LSP node. As such, the egress LSP node uses LDP to distribute the relevant labels to the relevant nodes. Once a DTU arrives at the ingress LSP mode, the DTU is thus forwarded to the egress LSP node based on the forwarding decisions dictated by the distributed labels.

[0006] An LDP is a specification that allows a label switch router (LSR) to distribute labels to its LDP pears. In MPLS, since DTUs are routed based on the labels carried by the DTUs, the routers (LSR) must know where to route the DTUs based on the labels

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carried by the DTU. Thus, if an LSR assigns a label A to a class of DTUs, that LSR must notify the other LSRs of the meaning of that label A (i.e. What to do or how to process or route a DTU with label A). This is accomplished by using an LDP. Since a set of labels from the ingress LSR (entry router) to the egress LSR (exit router) in an MPLS network defines a Label Switched Path (LSP), LDFs help in establishing an LSP by using a set of procedures to distribute the labels among the LSP peers (i.e. the ingress LSP and the egress LSPs are peers in that they communicate with each other at the same level - they can change what each has done).

[0007] From the above discussion, any solution to the above performance determination problem should ideally make use of the existing infrastructure that adheres to the MPLS standard. Such a solution would not require increased logic to be implemented and should allow for segmentation of LSPs in terms of performance and fault isolation.

100001 It should be noted that the term data transmission unit (DTU) will be used in a generic sense throughout this document to mean units through which digital data is transmitted from one point in a network to another. Thus, such units may take the form of packets, cells, frames, or any other unit as long as digital data is encapsulated within the unit. Thus, the term DTU is applicable to any and all packets and frames that implement specific protocols, standards or transmission schemes. It should also be noted that the term digital data will be used throughout this document to encompass all manner of voice, multimedia content, video, binary data or any other form of data or information that has been digitized and that is transmitted from one point in a

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network to another as a payload of a data transmission unit.

Summary of the Invention

The present invention seeks to provide methods for logically segmenting an LSP so that CAM DTUs may be used to determine the performance and/or the status of LSP segments. To segment a previously determined LSP, a dedicated subpath (a logical LSP) within that predetermined LSF is defined between two LSRs that are capable of processing OAM DTUs. The source node (source LSR) establishes a logical LSP between itself and the destination node (destination LSR) using an LDP. In doing this, the logical LSP traverses a specific path and transits through specific nodes in that path. The destination node then transmits an OAM DTU or any other specialized DTU to the source node using a label specifically associated with the logical LSF that was established. The characteristic of the specific path traversed by the logical LSP can thus be determined by when, how, and if the specialized DTU is received by the destination node.

[00010] In a first aspect the present invention provides a method of routing a special type of a data transmission unit between a source node and a destination node in a network that only allows unidirectional routing, both the source node and the destination node being capable of processing the special type of data transmission unit, the method comprising:

 a) selecting intermediate nodes to be traversed transmitted by the DTU when transmitted from the source node to the destination node;

b) designating the intermediate modes selected in step a) as being in a specific path of

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nodes between the source node and the destination node:

c) creating the DTU at the source node; and

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d) transmitting the DTU from the source node to the destination node along the specific path of nodes.

[00011] In a second aspect the present invention provides a method of segmenting a predefined path through a network that only allows unidirectional transmission, the method comprising:

- a) determining which nodes on the network are on the predefined path;
- b) defining segment nodes that define
 beginning and ending nodes for a network segment; and
- c) configuring a network segment between beginning and ending nodes by instructing intervening nodes on how to forward data transmission units configured for that network segment.
- [00012] In a third aspect the present invention provides a method of determining a performance of a network path, the method comprising:
- a) dividing the network path into segments, each segment having a source node defining a beginning of the segment and a destination node defining an ending of the segment;
- b) transmitting a specialized data transmission unit from the source node to the destination node;
- c) receiving the specialized data transmission unit at the destination node; and
- d) calculating the performance of the segment based on data contained in the specialized data transmission unit.

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[00013] In a fourth aspect the present invention provides a method of determining a performance of a network path, the method comprising:

- a) dividing the network path into segments, each segment having a source node defining a beginning of the segment and a destination node defining an ending of the segment;
- b) transmitting a specialized data transmission unit from the source node to the destination node; and
- c) determining if there is a fault on the segment based on Whether the specialized data transmission unit is received by the destination node within a given amount of time.

[00014] In a fifth aspect the present invention provides a network router for routing data transmission units (DTUs) in a domain which only allows unidirectional flow, the router including:

- a receiving module for receiving DTUs;
- a transmitting module for transmitting

DTUs:

- a switch core module placed between the receiving module and the transmitting module for routing DTUs between the receiving and the transmitting modules; and
- a diagnostic module for determining a performance of a network path of the domain, the diagnostic module being for processing specialized DTUs received by the receiving module and for creating specialized DTUs to be transmitted by the transmitting module,

wherein the router executes computer readable and computer executable instructions for implementing a mathod for determining the performance of the network path, the method including:

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- a) if the network router is a source node for the network path, transmitting the specialized DTUs to a destination node; and
- b) if the network router is a destination node for the network path, receiving the specialized DTUs and performing an action chosen from the group consisting of:
 - bl) calculating the performance of the network path based on data contained in the specialized DTU; and b2) determining if there is a fault on the network path based on whether a specialized DTU is received within a given amount of time.

Bricf Description of the Drawings

[00015] A better understanding of the invention may be obtained by reading the detailed description of the invention below, in conjunction with the following drawings, in which:

[00016] Figure 1 is a block diagram of an MPLS network using label switched routers;

[00017] Figure 1A is a block diagram illustrating the logical adjacencies allowed by OAM wrappers;

[00018] Figure 2 is a flowchart illustrating the steps in a method according to one aspect of the invention;

[00019] Figure 3 is a diagram of the fields in an MPLS DTU which may be used for transporting OAM data between LSRs; and

[00020] Figure 4 is a block diagram of the components a Label Switched Router (LSR) which may be used to implement one aspect of the invention.

Detailed Description

[00021] For this document, the term "QAM capable" will be understood to mean capable of processing QAM DTUs or some other specialized DTU used for maintenance and/or performance determination purposes. Processing such DTUs may involve producing such DTUs, determining network segment performance from the DTUs and determining network or network segment faults by the receipt of non-receipt of such DTUs. Based on the above, a "non-QAM capable" node will thus be nodes that are unable to process such specialized DTUs.

Referring to Figure 1, a schematic block diagram of an MPLS network 10 is illustrated. A first OAM capable LSR 20 (LSR0) is coupled to a node 30. The node 30 is coupled to another node 40 which, in turn, is coupled to a second OAM capable LSR 50 (LSR5). At another end of LSR 20, a non OAM capable LSR 60 (LSR1) is coupled to LSR 20 through two intervening nodes 70, 80. This non-CAM capable LSR 60 is also coupled to another OAM capable LSR 90 (LSR6) with no intervening nodes in between. At another port of LSR 60, another non-OAM capable LSR 100 (LGR4) is coupled to LSR 60 with three intervening nodes 110, 120, 130 in between. This LSR 100 is coupled, in turn, to LSR 90 with three intervening nodes 140, 150, 160 in between. At yet another port of LSR 60, this LSR 60 is coupled to an OAM capable LSR 170 (LSR2) through one intervening node 180. Between LSR 170 and an OAM capable LSR 190 (LSR3) are three intervening nodes 200, 210, 220. The LSK 190 is also coupled to LSR 100 at another of its ports.

[00023] It should be noted that intervening nodes 30, 40, 70, 80, 180, 140, 150, 160, 110, 120, 130,

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200, 210, 220 are not of interest and are merely network nodes that are non-OAM capable. For non-OAM capable nodes and LSRs OAM is transparent to these nodes and LSRs. These nodes are provided as illustration that other nodes may be present between the relevant LSRs.

[00024] With the network 10 as illustrated in Figure 1, proviously suggested solutions to the problem outlined above would only be capable of determining end-to-end performance between an ingress LSR and an euress LSR of an LSP. If the LSP was a path from LSRO to LSR3, with the LSP passing through LSR1 and LSR2, then only the performance for the whole path through LSR1 and can be found. The isolation of any faults in that path is not possible. Thus, if the node 100 were to fail, then a user would only know that the LSP between ISRO and LSR3 has failed and that upor would not be able to isolate the problem to any specific portion of the path. [00025] Segmentation of the MPLS network is achieved by configuring logical LSPs within a given

achieved by configuring logical LSPs within a given LSP. If the example given above of an LSP with LSRO as an ingress LSR and LSR3 as an egress LSR is taken, logical subsidiary LSPs can be created within this LSP. Since this LSP passes through an ORM depable LGR, LSR2, this LSR can be the breakpoint within the larger LSP. Thus, a subsidiary logical LSP between LSRO and LSR2 can be created and another subsidiary logical LSP pagment between LSR2 and LSR3 can be created.

[00026] By setting up a local LSP segment between LSRO and LSR2, any faults in that network segment can therefore be isolated. Similarly, if there is a fault between LSR2 and LSR3, then the fault can be isolated to that segment. If the MPLS network cannot

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be segmented between the ingress LSRO and the egress LSRS, then any fault between these two LSRs cannot be localized. If the MFLS network can be segmented, then by checking each segment the problem can be isolated.

[00027] To segment the LSP between LSRO and LSR3, the source node, in this case LSRO, would create an LSP segment between itself, LSRO, and the closest OAM capable LSR. In this case the nearest CAM capable LSR would be LSR2. An LSP segment between LSR0 and LSRI would not be of any use given that LSRI cannot process the OAM or specialized DTU. To provision this first LSP segment, LSRO would use the LDP to notify all the nodes between itself and the destination node that a new LSP segment has been established and that any DTUs carrying the label that is assigned to the new LSP segment must be processed accordingly. With the first subsidiary LSP established, a second LSP segment can be created between LSR2 and LSR3. This second LSF segment would be useful as it is between OAM capable LSRs. It should be clear that these LSP segments are being defined within an LSP that has been previously established. The LSP segments are denoted as an attribute of this previously established LSP. The LSP segments are defined when the original LSP is defined. In effect, an "OAM wrapper" is established for each possible segment as an attribute of that LSP. Thus, if a path for an LSP changes, the new labels distributed to setup the new path will carry with it the CAM wrapper attribute of the LSP. LSP segments are defined and for each LSP segment delimited by OAM capable LSRs or non OAM LSP segments (e.g. LSR1 in Figure 1), an OAM wrapper can be established. Thus, in Figure 1, the LSP segment defined between OAM capable LSRs, LSR2 and LSR3 can

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To establish the second LSP segment the

have an OAM wrapper associated with it. Similarly, the LSP segment between LSRO and LSR2 can have its own OAM wrapper associated with it.

source node, either of LSR2 or LSR3, can initiate the process by provisioning for the LSP segment and using LDP to notify the nodes between itself and the destination LSR how DTUs with the label for this second LSP segment will be processed. Once these two LSP cogments are established, it should be clear that any problems in the original LSP between LSRO and ISR3 can he localized to either of the two LSP segments. If there is a problem in the original LSP then this problem may be localized by using the LSP segments to pinpoint the problem. The first LSP segment between LSRO and LSR2 can be activated and LSRO can send a specialized fault detection DTU or a regular OAM DTU to LSR2 to determine if the fault is within that segment of the original LSP. Simultaneously, the second LSP segment between LSR2 and LSR3 can be examined by having the destination node send a similar fault detection or CAM DTU to the destination LSR to determine if the fault is within that segment. By this process of segmentation and elimination, faults along a previously determined LSP

[00029] Again taking Figure 1 as an example, the CAN wrappers that can be established are as follows: CAN wrapper A:

can be localized and isolated.

between LSRO (ingress) and LSR5 (egress) OAM wrapper B:

between LSR6 (ingress) and LSR3 (egress) OAM wrapper C:

between LSR1 (ingress) and LSR2 (egross) OAM wrapper D:

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between LSR7 (ingress) and LSR3 (egress) The OAM wrapper establishes logical 1000301 adjacencies between LSRs that are equipped with OAM capabilities for performance measurement and fault isolation. The ingress and egress points are set out clearly in the OAM wrapper satup to account for the unidirectional nature of MPLS. The logical links or adjacencies between the CAM capable LSRs are illustrated in Figure 1A. As can be seen in Fig 1A, LSRO is logically adjacent to LSRS, LSR2, LSR3, and LSR6 for UAM purposes. Furthermore, LSR6 is logically adjacent to LSR3 and LSR2 is also logically adjacent to LSR3 for OAM purposes. The intervening nodes between these LSRs are non-OAM capable and are thus transparent to the OAM DTUs and are not included in Figure 1A. Also, since LSR1 and LSR4 are non-OAM capable, these are also transparent to CAM and CAM DTUs and are not included in Figure 1A. As part of the establishment of a LSP

[00031] As part of the establishment of a 1.5P segment, at least one label has to be assigned to the LSP segment. This involves the establishing node, usually the source LSR, choosing a label in the LSP segment. Once this label is chosen, it is then assigned to the LSP segment. Once assigned the label can then be inserted into the OAM DTU. It should be noted that this assignment is communicated to the other nodes using LDP. This way the other nodes are notified of the new label and of the new LSP segment.

[00032] To ensure that a LSP segment will traverse a specific path through the network, the LSP segment can be configured to proceed along a specific path. As an example, if an LSP between LSRO and LSR3 is configured to travel any path between LSRO and LSR3 them multiple possibilities exist for this path.

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For example a DTU on that LSP, which we can label as the primary LSP, can take the path from LSRO to LSRI, then to LSR6, LSR4, and finally, to LSR3. Or, that same DTU may take the path from LSRO to LSRI, then to LSR2, and finally to LSR3. As a third path the DTU could travel from LSRO, in to LSR1, LSR4, and, finally, to LSR3. Clearly, to perform fault management and/or performance determination and management on the primary LSP petween LSRO and LSR3 in this configuration can be difficult. However, if LSPs segments are created between the CAM capable LSRs in this configuration, then both fault management and performance determination is simplified. As an example, an LSP subsidiary can be created between LSRO and LSR6 passing through LSR1. Similarly, a LSP segment can be created between LSR6 and LSR3 passing through LSR4. Also, an LSP segment can be created between LSRO and LSRO passing through ISR1 and LSR4. To ensure that the correct path is being created and examined, the LSP between the CAM capable LSRs can be created to follow a very specific path. As an example, an LSP occment between LSR6 and LSR3 can be created by using LDP to notify all the nodes that a DTU passing through this LSP must pass through node 140, 150, 160 and LSR4. Similarly, if an LSP segment between LSRO and LSRS is to be created to test the links between LSR1 and LSR4, then this LSP segment should be configured such that any DTU on this LSP must pass through nodes 110, 120, and 130, Concorning the NAM DTU that may be [00033] transmitted from a source node to a destination node. this CAM DTU can be created in a well known manner and designed according to a user's specific need. To further clarify it should be noted that a source node and a destination node are ideally CAM capable LSRs.

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An LSR is a node that can route traffic based on their labels.

[00034] The CAM DfU can be as simple as a DfU that has a date and time stamp of when the DTU was transmitted from a source node. This CAM DTU, when received by the destination node, is processed by merely reading the date and time stamp and comparing that with the date and time at which the OAM DTU was received at the destination node. By doing this comparison, the transit time from the source node to the destination node can be determined as long as, of course, the clocks in the source node and the destination node are substantially synchronized. For fault isolation, the source node can send a confirmation CAM DTU to a destination node. The faults on the LSP segment can be found if the confirmation DTU is not received by the destination node. This fault detection can be continuously carried out with the source node of the JSP segment sending a confirmation OAM DTU to the multiple destination nodes at a specified rate. The destination node can, based on the average transit time for an OAM DTU, determine if the source node transmitting the confirmation CAM DTUs is still communicating. If a destination node does not receive a contirmation CAM DTU within a predetermined amount of time after the previous confirmation OAM DTU, then the destination node may decide to issue a warning that a fault on the LSP segment of the primary LSP is present. This will therefore allow usors and/or network management software to look further into the matter. rigure 2 is a flow chart illustrating the

[00035] Figure 2 is a flow chart illustrating the steps taken in the process outlined above is illustrated. The first step is step 230. This step

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chooses the primary LSP to be segmented. Step 240 determines the path in the primary LSP for an LSP segment. As an example, in Figure 1, if the primary LSP is from LSR0 to LSR3 then the second step would be to determine whether the LSP segment passes through LSRO, LSR1, and LSR2 or through LSRO, LSR1, LSR4 and, finally, LSR 3. After this, the next step (step 250) is that of provisioning or allowing for an LSP segment to be established. This step involves determining the label to be assigned to the LSP segment and allocating resources for this label to be assigned. Step 260 involves notifying the other nodes and LSRs in the MPLS network about the LSP segment being created. This notification is normally done using LDP. This notification notifies the nodes in the path of the LSP segment about how packets having the label assigned to that LSP segment is to be furwarded and or processed.

[00036] Once the LSP segment has been setup by assigning the label for that LSP and by notifying the nodes in the LSP segment, the source node or the source LSR can now create the OAM DTU and/or the specialized DTU for transmission to the destination node (step 265). Step 270 is then that of actually transmitting the OAM DTU from the source node to the destination node along the LSP segment. Step 280 receives the OAM DTU at the destination node. This step assumes that the OAM DTU arrives at the destination node and that there is no fault along the LSP segment. Finally, step 290 is that of processing the OAM DTU at the destination node to determine the performance of the LSP segment and/or to determine the configuration of the LSP segment.

for MPLS Drus is illustrated. As can be seen, a PPP

Referring to Figure 3, a possible format

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(Point-to-Point Protocol) field 300 provides for data related to the PPP protocol While a transport label field 310 and a service label field 320 allows the DTU to be used in an MPLS domain. The contents of the transport label filed 310 determines the routing of the DTU while the contents of the service label field 320 determines the service or processing provided to the DTU. The OAM label field 325 carries an OAM label which signals to the destination node that it is an OAM DTU. The inclusion of this field is in accordance with the document ITU-T.1711. The payload 330 contains any data to be transported while the CRC field 340 provides error correction for the DTU. If the DTU is to be used as an CAM DTU, then any data which may be needed by an OAM DTU may be laced in the payload field 330. The OAM wrapper discussed above would be evidenced by an OAM label in the CAM label field 325. An CAM capable LSR which processes the DTU would recognize the specialized OAM label and process the DTU accordingly. Non-OAM capable nodes (such as nodes 140, 150 in Figure 1) would not recognize the specialized CAM label and would merely forward the OAM DTU to the next node. Referring to Figure 4, illustrated is a block diagram of an OAM mapable MPLS router (LSR) which may use the invention.

[00039] As can be seen in Figure 4, the router 400 has three main components: an input module 410, a switch core 420, and an output module 430. The input module 410 receives DTUo from downstream nodes. The switch core 420 then switches these DTUs to the proper eyress ports on the output module 430. Prior to forwarding the received DTU, the LSR processes the DTU. If the DTU is an QAM DTU, then the LSR may response to the CAM DTU to indicate that the QAM DTU

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has arrived. It is at this point that the router implements the invention as explained above. The implementation can be carried out by the output module 430 prior to transmitting the CAM DTUs across the MPLS domain. Alternatively, an extra MPLS module 440 may be provided between the output module that would process the OAM DTUs and ensure that such OAM DTUs are properly processed, sent or responded to. Furthermore, such an CAM module would ensure that the MPLS transport of the CAM DTUs is properly provisioned. To this end, the MPLS module would handle the signalling and LDP execution to implement the invention. The OAM module would therefore perform the processing, signalling, encapsulation, and service label allocation that are outlined above. It should be clear that the above description for Figure 4 applies to a source node for an OAM DTU. This source node LSR would originate and transmit the CAM DTU to a destination DTU that would receive the CAM DTU.

[00040] If the OAM capable LSR is a destination node, the parts of this destination node are the same as those illustrated in Figure 4 except that the MPLS module would be placed such that the receive module 410 is between the MPLS module 440 and the owitch core 420. Such a destination node would receive OAM DTUs and, prior to processing them as regular DTUs, would process them as OAM DTUs.

[00041] Embodiments of the invention may be implemented in any conventional computer programming language. For example, preferred embodiments may be implemented in a procedural programming language (e.g. "C") or an object oriented language (e.g. "C++"). Alternative embodiments of the invention may be implemented as pre programmed hardware elements,

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other related components, or as a combination of hardware and software components.

[00042] Embodiments can be implemented as a computer program product for use with a computer system. Such implementation may include a series of computer instructions fixed either on a tangible modium, such as a computer readable medium (e.g., a diskette, CD-ROM, ROM, or fixed disk) or transmittable to a computer system, via a modem or other interface device, such as a communications adapter connected to a network over a medium. The medium may be either a tangible medium (c.g., optical or electrical communications lines) or a medium implemented with wireless techniques (e.g., microwave, infrared or other transmission techniques). The series of computer instructions embodies all or part of the functionality previously described herein. Those skilled in the art should appreciate that such computer instructions can be written in a number of programming languages for use with many computer architectures or operating Systems. Furthermore, such instructions may be stored in any memory device, such as semiconductor, magnetic, optical or other memory devices, and may be transmitted using any communications technology, such as optical, infrared, microwave, or other transmission technologies. It is expected that such a computer program product may be distributed as a removable medium with accompanying printed or electronic documentation (e.g., shrink wrapped software), preloaded with a computer system (e.g., on system ROM or fixed disk), or distributed from a server over the network (e.g., the Internet or World Wide Web). Of course, some embodiment of the invention may be implemented as a combination of both software (c.g. a computer program product) and

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hardware. Still other embodiments of the invention may be implemented as entirely hardware, or entirely software (e.g. a computer program product).